Large-Scale Characteristic Mode Analysis With Fast Multipole Algorithms

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Abstract-Large-scale characteristic mode analysis (CMA) poses challenges in computational electromagnetics as it calls for efficient solutions of large dense generalized eigenvalue problems. In this paper, we consider two applications that involve large-scale CMA, and demonstrate that fast multipole algorithms (FMAs) can be easily incorporated into the implicitly restarted Arnoldi method (IRAM) for eigenanalysis after simple modifications. The first application performs CMA for large platforms made by closed perfectly conducting surfaces. Multilevel FMA (MLFMA) is embedded into a combined field integral equationbased theory of characteristic mode (TCM). The second application addresses multiscale modeling of small but geometrically complicated objects, which possess fine subwavelength structures. An augmented electric field integral equation-based TCM is formulated, and low-frequency (LF-)FMA is adopted to accelerate the required matrix-vector products.

Index Terms—Augmented electric field integral equation, characteristic mode, combined field integral equation, fast multipole algorithm (FMA), large scale.

I. INTRODUCTION

FTER its humble beginnings in the 1970s, characteristic mode analysis (CMA) has gained a recent resurgence of interest in the field of antenna design and optimization. Initiated by Garbacz and refined by Harrington and Mautz [1]–[3], CMA was popularized in the antenna community by the work of Cabedo–Fabrés, as it has been shown promising for systematic antenna design [4]. Such a systematic approach becomes increasingly favored, since heuristic approaches based on the experience and intuition of antenna engineers hardly survive the demanding requirement of designing complex antenna systems. CMA is capable of characterizing an arbitrary object's radiation and scattering properties only relying on its geometry and material properties rather than the source configuration,

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which makes it a favorable candidate for systematic design methods where complicated functionality tradeoffs can be handled. Moreover, CMA provides useful physical insight into antenna operation as well as guidance on the excitation of desired radiating modes [5]–[7].

Although CMA has shown success in antenna design and synthesis, a relatively little effort has been devoted to characteristic mode computation. Development of new theory of characteristic mode (TCM) becomes indispensable in various large-scale applications where the conventional theory based on an electric field integral equation (EFIE) fails to properly function. One example is an automotive antenna where a coupling element excites multimodes of a large platform (closed vehicle chassis), and the entire platform operates as an antenna [8]. In this case, the conventional theory suffers from the spurious internal resonance corruption [9]. Another example is multiscale modeling of a small complex geometry, such as a metamaterial-inspired antenna. Due to the existence of fine subwavelength structures, a portion or all of the mesh elements are of small electrical size, which normally results in a large number of unknowns. In this case, the conventional theory may be susceptible to a low frequency or dense mesh breakdown [10].

Regarding computational complexity, current strategies of CMA can only deal with small-scale problems as they explicitly generate EFIE impedance matrices. The memory cost is $O(N^2)$, where N is the number of unknowns resulted from the method of moment (MoM). The complexity of computing all eigenpairs (eigenvalues and eigenvectors) of a dense generalized eigenvalue problem is $O(N^3)$ with QZ factorization. Normally, it is not the entire eigenspectrum that is of interest. The desired spectral portion, i.e., small eigenvalues, corresponds to efficient radiating modes that dominate the induced current excited by an arbitrary source [4], [11]. This portion can be iteratively solved for using Krylov subspace methods such as Lanczos or Arnoldi algorithms [12]-[14]. A number of matrix vector products (MVPs) are performed in such methods, each of which has a computational complexity of $O(N^2)$. Even so, this $O(N^2)$ complexity hinders large-scale CMA in the aforementioned applications.

It is well known that fast multipole algorithms (FMAs) can be used to accelerate MVPs in large-scale EM scattering problems, among which the multilevel version based on translation, interpolation, anterpolation, and a grid-tree structure greatly reduces both computational and memory costs of MVPs to $O(N \log N)$ [15]–[19]. In this paper, we address large-scale CMA by embedding FMAs into iterative eigensolvers such as the implicitly restarted Arnoldi method (IRAM) [12], [13]

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and/or the Jacobi–Davidson QZ (JDQZ) method [14]. To analyze a large closed platform, a combined-field integral equation (CFIE)-based TCM is employed to remove the spurious internal resonance corruption. Multilevel FMA (MLFMA) is modified to accelerate the required MVPs. On the other hand, to remedy the difficulty in multiscale modeling of small complex geometries, we reformulate TCM on the top of an augmented electric field integral equation (A-EFIE) [10], and accelerate the required MVPs with a low-frequency (LF-) FMA [20]. Numerical examples are presented to validate and demonstrate the performance of the proposed schemes. This work paves the way of CMA for large-scale and complicated 3-D objects with limited computational resources.

II. TCM BASED ON EFIE

As suggested by Harrington and Mautz [3], the characteristic mode theory for an arbitrarily shaped perfectly conducting surface S is formulated on top of EFIE as

$$\mathcal{X}_E(\mathbf{r},\mathbf{r}') \cdot \mathbf{J}_n(\mathbf{r}') = \lambda_n \mathcal{R}_E(\mathbf{r},\mathbf{r}') \cdot \mathbf{J}_n(\mathbf{r}') \quad \mathbf{r} \in S \quad (1)$$

where λ_n and \mathbf{J}_n correspond to the characteristic values and currents, respectively. Note that integration is implied over repeated variables in this paper. The real and imaginary parts of the EFIE impedance operator \mathcal{Z}_E are denoted by \mathcal{R}_E and \mathcal{X}_E , respectively. The impedance operator applies to a surface current as

$$\mathcal{Z}_{E}(\mathbf{r},\mathbf{r}')\cdot\mathbf{J}(\mathbf{r}') = -\overline{\mathbf{I}}_{t}\cdot ik\eta \int_{S} d\mathbf{r}'\overline{\mathbf{G}}(\mathbf{r},\mathbf{r}')\cdot\mathbf{J}(\mathbf{r}') \qquad (2)$$

where k is the wavenumber, $\eta = \sqrt{\mu/\varepsilon}$ is the characteristic impedance of free space, and $\overline{\mathbf{I}}_t = \overline{\mathbf{I}} - \hat{n}\hat{n}$ extracts the tangential components of the field with $\overline{\mathbf{I}}$ denoting a unit dyad, \hat{n} the unit normal of the surface. In the above, and Green's dyad is

$$\overline{\mathbf{G}}(\mathbf{r},\mathbf{r}') = \left[\overline{\mathbf{I}} - \frac{\nabla\nabla'}{k^2}\right]g(\mathbf{r},\mathbf{r}')$$
(3)

with

$$g(\mathbf{r}, \mathbf{r}') = \frac{e^{ikR}}{R} \quad R = |\mathbf{r} - \mathbf{r}'|.$$
(4)

Approximating the surface current $\mathbf{J}(\mathbf{r})$ with Rao–Wilton– Glisson (RWG) basis functions $\mathbf{f}_j(\mathbf{r})$, we obtain the matrix representation of \mathcal{Z}_E as

$$[Z_E]_{ij} = -ik\eta \int_s d\mathbf{r} \, \mathbf{f}_i(\mathbf{r}) \cdot \int_s \overline{\mathbf{G}}(\mathbf{r}, \mathbf{r}') \cdot \mathbf{f}_j(\mathbf{r}') \, d\mathbf{r}' \quad (5)$$

with Galerkin's procedure where testing functions are chosen to be the same as basis functions. Equation (1), therefore, leads to a generalized eigenvalue problem as

$$\overline{\mathbf{X}}_E \cdot \mathbf{J}_n = \lambda_n \overline{\mathbf{R}}_E \cdot \mathbf{J}_n \tag{6}$$

where the resistance and reactance matrices $\overline{\mathbf{R}}_E$ and $\overline{\mathbf{X}}_E$ correspond to the real and imaginary parts of the impedance matrix $\overline{\mathbf{Z}}_E$, respectively.

Usually, one can obtain good approximations to the eigenvalues with large magnitudes using Krylov subspace iterations [13]. It is hence straightforward, as suggested in the ARnoldi PACKage (ARPACK) [13], or implemented in the commercial suite FEKO [11], to convert (6) to a standard eigenvalue problem as

$$\overline{\mathbf{X}}_{E}^{-1} \cdot \overline{\mathbf{R}}_{E} \cdot \mathbf{J}_{n} = \lambda_{n}^{-1} \mathbf{J}_{n}$$
(7)

for fast convergence to desired eigenspectra (small eigenvalues), which correspond to efficient radiating modes. A number of MVPs in the form of $\overline{\mathbf{X}}_E^{-1} \cdot \mathbf{u}$ have to be computed, where \mathbf{u} are the arbitrary vectors. If $\overline{\mathbf{X}}_E^{-1} \cdot \mathbf{u}$ is solved iteratively, it is favored to solve an equivalent eigenvalue problem given by

$$\overline{\mathbf{Z}}_{E}^{-1} \cdot \overline{\mathbf{R}}_{E} \cdot \mathbf{J}_{n} = (1 + i\lambda_{n})^{-1} \mathbf{J}_{n}$$
(8)

since efficient preconditioners exist for expediting iterative convergence to EFIE solutions $\overline{\mathbf{Z}}_{E}^{-1} \cdot \mathbf{u}$.

III. TCM BASED ON CFIE

Conventional EFIE-based TCM can hardly be used to solve for characteristic modes of large closed platforms, where $\overline{\mathbf{Z}}_E$ are ill-conditioned due to spurious internal resonances. In a recent paper, we formulated a CFIE-based TCM as [9], [21]

$$\begin{aligned} & [\alpha \mathcal{Z}_E(\mathbf{r}, \mathbf{r}') + (1 - \alpha)\eta \mathcal{Z}_H(\mathbf{r}, \mathbf{r}')] \cdot \mathbf{J}_n(\mathbf{r}') \\ &= (1 + i\lambda_n) \left[\alpha \mathcal{R}_E(\mathbf{r}, \mathbf{r}') + (1 - \alpha)i\eta \mathcal{X}_H(\mathbf{r}, \mathbf{r}') \right] \cdot \mathbf{J}_n(\mathbf{r}') \end{aligned}$$
(9)

where $\mathbf{r} \in S$, α is the CFIE combination coefficient, and \mathcal{X}_H is the imaginary part of the magnetic field integral operator \mathcal{Z}_H , which is given by

$$\mathcal{Z}_{H}(\mathbf{r},\mathbf{r}')\cdot\mathbf{J}(\mathbf{r}') = 2\pi\overline{\mathbf{I}}_{t}\cdot\mathbf{J}(\mathbf{r}) - \overline{\mathbf{I}}_{t}\cdot\hat{n} \\ \times P.V.\int_{S}d\mathbf{r}'\nabla g(\mathbf{r},\mathbf{r}')\times\mathbf{J}(\mathbf{r}').$$
(10)

After discretizing (9), one can obtain the matrix eigenvalue equation as

$$\overline{\mathbf{Z}}_C \cdot \mathbf{J}_n = (1 + i\lambda_n)\overline{\mathbf{M}}_C \cdot \mathbf{J}_n \tag{11}$$

where

$$\overline{\mathbf{Z}}_C = \alpha \overline{\mathbf{Z}}_E + (1 - \alpha) \eta \overline{\mathbf{Z}}_H$$
(12a)

$$\overline{\mathbf{M}}_C = \alpha \overline{\mathbf{R}}_E + (1 - \alpha)i\eta \overline{\mathbf{X}}_H.$$
(12b)

In the above, $\overline{\mathbf{Z}}_E$ and $\overline{\mathbf{R}}_E$ have the same definition as before, while $\overline{\mathbf{Z}}_H$ and $\overline{\mathbf{X}}_H$ are the matrix representations of operators \mathcal{Z}_H and \mathcal{X}_H , respectively. For simplicity, RWG functions are adopted herein to discretize the magnetic field integral operator, such that

$$[Z_H]_{ij} = 2\pi \int_s d\mathbf{r} \, \mathbf{f}_i(\mathbf{r}) \cdot \mathbf{f}_j(\mathbf{r}) - \int_s d\mathbf{r} \, \mathbf{f}_i(\mathbf{r}) \cdot \hat{n} \times \nabla \times \int_s g(\mathbf{r}, \mathbf{r}') \mathbf{f}_j(\mathbf{r}') \, d\mathbf{r}'.$$
(13)

Otherwise, Buffa–Christiansen (BC) or Chen–Wilton (CW) basis functions can be used as the testing functions for a better discretization accuracy [22]–[24]. Since $\overline{\mathbb{Z}}_C$ is full rank even at frequencies of internal resonances, we convert (11) to a standard eigenvalue equation as

$$\overline{\mathbf{Z}}_{C}^{-1} \cdot \overline{\mathbf{M}}_{C} \cdot \mathbf{J}_{n} = (1 + i\lambda_{n})^{-1} \mathbf{J}_{n}$$
(14)

which can be easily solved using iterative methods.

IV. TCM BASED ON A-EFIE

In multiscale modeling, an electrically small object may result in a large number of unknowns due to the dense discretization on its fine subwavelength parts. This renders $\overline{\mathbf{Z}}_E$ ill-conditioned, and hinders solving $\overline{\mathbf{Z}}_E^{-1} \cdot \mathbf{u}$ iteratively. In excitation problems, this difficulty has been remedied with an augmented EFIE (A-EFIE) [10].

In light of the following decomposition:

$$\overline{\mathbf{Z}}_E = ik\eta\overline{\mathbf{V}} + \frac{\eta}{ik}\overline{\mathbf{D}}^T \cdot \overline{\mathbf{P}} \cdot \overline{\mathbf{D}}$$
(15)

with definitions of matrices $\overline{\mathbf{V}}$, $\overline{\mathbf{P}}$, and $\overline{\mathbf{D}}$ provided in [10], the EFIE-based TCM can be reformulated on top of A-EFIE as

$$\overline{\mathbf{Z}}_{A} \cdot \begin{bmatrix} ik\mathbf{J}_{n} \\ c\boldsymbol{\rho}_{n} \end{bmatrix} = (i - \lambda_{n})\overline{\mathbf{X}}_{A} \cdot \begin{bmatrix} ik\mathbf{J}_{n} \\ c\boldsymbol{\rho}_{n} \end{bmatrix}$$
(16)

or

$$\overline{\mathbf{R}}_{A} \cdot \begin{bmatrix} ik\mathbf{J}_{n} \\ c\boldsymbol{\rho}_{n} \end{bmatrix} = -\lambda_{n}\overline{\mathbf{X}}_{A} \cdot \begin{bmatrix} ik\mathbf{J}_{n} \\ c\boldsymbol{\rho}_{n} \end{bmatrix}$$
(17)

where $c^{-1} = \sqrt{\mu\epsilon}$, and \mathbf{J}_n and $\boldsymbol{\rho}_n$ are the characteristic currents and charges, respectively. By explicitly enforcing the charge neutrality condition, we have

$$\overline{\mathbf{Z}}_{A} = \begin{bmatrix} \overline{\mathbf{V}} & \overline{\mathbf{D}}^{T} \cdot \overline{\mathbf{P}} \cdot \overline{\mathbf{B}} \\ \overline{\mathbf{F}} \cdot \overline{\mathbf{D}} & k^{2} \overline{\mathbf{I}} \end{bmatrix}$$
(18)

where $\overline{\mathbf{F}}$ and $\overline{\mathbf{B}}$ are forward and backward mapping matrices between full and reduced charge vectors, respectively, and $\overline{\mathbf{I}}$ is an identity matrix of reduced dimension, as defined in [10]. Besides, $\overline{\mathbf{X}}_A$ and $\overline{\mathbf{R}}_A$ are the imaginary and real parts of $\overline{\mathbf{Z}}_A$, respectively.

Again, it is convenient to transform (16) into a standard eigenvalue problem as

$$\overline{\mathbf{Z}}_{A}^{-1} \cdot \overline{\mathbf{X}}_{A} \cdot \begin{bmatrix} ik\mathbf{J}_{n} \\ c\boldsymbol{\rho}_{n} \end{bmatrix} = (i - \lambda_{n})^{-1} \begin{bmatrix} ik\mathbf{J}_{n} \\ c\boldsymbol{\rho}_{n} \end{bmatrix}$$
(19)

where the A-EFIE solution $\overline{\mathbf{Z}}_{A}^{-1} \cdot \mathbf{u}$ can be computed iteratively with a constraint preconditioning scheme. The same process is also applicable to (17).

V. FMA FOR CMA

In large-scale applications, characteristic modes of interest are normally solved for iteratively. ARPACK, based on the IRAM or the Lanczos variant for symmetric matrices, is appropriate for calculating a few eigenpairs of large sparse or structured matrices, where an MVP requires only O(N) floating point operations [12]. However, when ARPACK is applied to dense eigenvalue problems, MVPs are challenged by the $O(N^2)$ complexity and storage requirement.

From (8), (14), and (19), the first type of required MVPs for constructing Arnoldi vectors are of forms $\overline{\mathbf{R}}_E \cdot \mathbf{u}$, $\overline{\mathbf{M}}_C \cdot \mathbf{u}$, and $\overline{\mathbf{X}}_A \cdot \mathbf{u}$ for EFIE-, CFIE-, and A-EFIE-based TCMs, respectively. The simplest approach to perform such MVPs is given by the following direct extraction.

Regarding an arbitrary vector \mathbf{u} , one can efficiently compute $\overline{\mathbf{Z}} \cdot \mathbf{u}$ with the conventional FMA, where $\overline{\mathbf{Z}} = \overline{\mathbf{R}} + i\overline{\mathbf{X}}$ is taken to be $\overline{\mathbf{Z}}_E, \overline{\mathbf{Z}}_H$, or $\overline{\mathbf{Z}}_A$. It is well known that midfrequency MLFMA reduces the computational complexity and memory cost of $\overline{\mathbf{Z}} \cdot \mathbf{u}$ to $O(N \log N)$, and the LF-FMA enables MVPs with an O(N) complexity [18]–[20]. Hence, for an arbitrary complex vector $\mathbf{u} = \mathbf{u}' + i\mathbf{u}''$, providing that $\overline{\mathbf{R}}$ and $\overline{\mathbf{X}}, \mathbf{u}'$, and \mathbf{u}'' are all real, the required MVPs can be computed with a simple algebraic approach as

$$\overline{\mathbf{R}} \cdot \mathbf{u} = \overline{\mathbf{R}} \cdot \mathbf{u}' + i\overline{\mathbf{R}} \cdot \mathbf{u}'' = \Re e \left[\overline{\mathbf{Z}} \cdot \mathbf{u}' \right] + i\Re e \left[\overline{\mathbf{Z}} \cdot \mathbf{u}'' \right]$$
(20)

and

$$\overline{\mathbf{X}} \cdot \mathbf{u} = \overline{\mathbf{X}} \cdot \mathbf{u}' + i\overline{\mathbf{X}} \cdot \mathbf{u}''$$
$$= \Im m \left[\overline{\mathbf{Z}} \cdot \mathbf{u}' \right] + i \Im m \left[\overline{\mathbf{Z}} \cdot \mathbf{u}'' \right]$$
(21)

where $\Re e[\cdot]$ and $\Im m[\cdot]$ take the real and imaginary parts of the argument in the parentheses, respectively. Moreover, regarding the CFIE-based theory, $\overline{\mathbf{M}}_C \cdot \mathbf{u}$ is computed as

$$\overline{\mathbf{M}}_{C} \cdot \mathbf{u} = \left[\alpha \overline{\mathbf{R}}_{E} + (1 - \alpha) i \eta \overline{\mathbf{X}}_{H} \right] \cdot (\mathbf{u}' + i \mathbf{u}'')
= \alpha \Re e \left[\overline{\mathbf{Z}}_{E} \cdot \mathbf{u}' \right] + i \alpha \Re e \left[\overline{\mathbf{Z}}_{E} \cdot \mathbf{u}'' \right]
+ (1 - \alpha) i \eta \Im m \left[\overline{\mathbf{Z}}_{H} \cdot \mathbf{u}' \right] + (\alpha - 1) \eta \Im m \left[\overline{\mathbf{Z}}_{H} \cdot \mathbf{u}'' \right].$$
(22)

A more involved approach to compute $\overline{\mathbf{M}}_C \cdot \mathbf{u}$ adapts the plane-wave decomposition. Consider a spatial vector from the source point \mathbf{r}_j in group m' to the observation point \mathbf{r}_i in group m such that

$$\mathbf{r}_{ij} = \mathbf{r}_i - \mathbf{r}_j = \mathbf{r}_i - \mathbf{r}_m + \mathbf{r}_m - \mathbf{r}_{m'} + \mathbf{r}_{m'} - \mathbf{r}_j$$

$$= \mathbf{r}_{im} + \mathbf{r}_{mm'} + \mathbf{r}_{m'j}$$
(23)

where \mathbf{r}_m and $\mathbf{r}_{m'}$ represent the centers of groups m and m'. We can derive the following plane-wave decomposition:

$$\frac{\sin(kr_{ij})}{r_{ij}} = \int d^2 \hat{k} \, e^{i\mathbf{k}\cdot(\mathbf{r}_{im}+\mathbf{r}_{m'j})} \, \alpha^{\Re}_{mm'}\left(\mathbf{k},\mathbf{r}_{mm'}\right) \tag{24}$$

where

$$\alpha_{mm'}^{\mathfrak{R}}\left(\mathbf{k},\mathbf{r}_{mm'}\right) = \frac{k}{4\pi} \sum_{l=0}^{L} i^{l} (2l+1) j_{l}(kr_{mm'}) P_{l}\left(\hat{k}\cdot\hat{r}_{mm'}\right)$$
(25)

with L as the truncation number of an infinite series, $j_l(\cdot)$ as the spherical Bessel function of order l, and $P_l(\cdot)$ as the Legendre polynomial of degree l.

As there is no violation of addition theorem for (24), the FMM calculation may involve both the nearby and non-nearby groups of group m (except for itself), and the required MVPs in terms of a two-level algorithm are obtained as

$$\sum_{j=1}^{N} [M_C]_{ij} u_j = \sum_{j \in G_m} [M_C]_{ij} u_j + k\eta \int d^2 \hat{k} \, \mathbf{V}_{fim}(\hat{k})$$
$$\cdot \sum_{m' \neq m} \alpha_{mm'}^{\mathfrak{R}}(\mathbf{k}, \mathbf{r}_{mm'})$$
$$\cdot \sum_{j \in G_{m'}} \mathbf{V}_{sm'j}(\hat{k}) u_j, \quad i \in G_m \qquad (26)$$

where

$$\mathbf{V}_{sm'j}(\hat{k}) = \int_{s} d\mathbf{r} \left(\overline{\mathbf{I}} - \hat{k}\hat{k} \right) \cdot \mathbf{f}_{j}(\mathbf{r}_{m'j}) e^{i\mathbf{k}\cdot\mathbf{r}_{m'j}}$$
(27)

and

$$\mathbf{V}_{fim}(\hat{k}) = \alpha \int_{s} d\mathbf{r} \left(\overline{\mathbf{I}} - \hat{k}\hat{k} \right) \cdot \mathbf{f}_{i}(\mathbf{r}_{im})e^{i\mathbf{k}\cdot\mathbf{r}_{im}} + (1-\alpha)\hat{k} \times \int_{s} d\mathbf{r} \,\hat{n} \times \mathbf{f}_{i}(\mathbf{r}_{im})e^{i\mathbf{k}\cdot\mathbf{r}_{im}}.$$
 (28)

Regarding the multilevel algorithm, the standard MLFMA bookkeeping can still be employed for convenience [19]. However, a more efficient implementation conducts translation between nearby groups that belong to the same parent group at each level. Besides, the coarsest level is taken to be level-1 rather than level-2.

In addition, if MVPs such as $\overline{\mathbf{X}}_E \cdot \mathbf{u}$ and $\overline{\mathbf{R}}_H \cdot \mathbf{u}$ are to be computed, the following plane-wave decomposition can be used on condition that m and m' are not nearby groups or $|\mathbf{r}_{im} + \mathbf{r}_{m'j}| < |\mathbf{r}_{mm'}|$:

$$\frac{\cos(kr_{ij})}{r_{ij}} = \int d^2 \hat{k} \, e^{i\mathbf{k}\cdot(\mathbf{r}_{im}+\mathbf{r}_{m'j})} \, \alpha_{mm'}^{\mathfrak{S}}\left(\mathbf{k},\mathbf{r}_{mm'}\right) \quad (29)$$

where

$$\alpha_{mm'}^{\mathfrak{S}}\left(\mathbf{k},\mathbf{r}_{mm'}\right) = \frac{-k}{4\pi} \sum_{l=0}^{L} i^{l} (2l+1) y_{l}(kr_{mm'}) P_{l}\left(\hat{k}\cdot\hat{r}_{mm'}\right)$$
(30)

with the spherical Neumann function $y_l(\cdot)$ of order *l*.

Accordingly, the second type of required MVPs are $\overline{\mathbf{Z}}_{E}^{-1} \cdot \mathbf{u}$, $\overline{\mathbf{Z}}_{C}^{-1} \cdot \mathbf{u}$, and $\overline{\mathbf{Z}}_{A}^{-1} \cdot \mathbf{u}$, which are the solutions of EFIE, CFIE, and A-EFIE under arbitrary excitation vectors \mathbf{u} , respectively. As EFIE solutions $\overline{\mathbf{Z}}_{E}^{-1} \cdot \mathbf{u}$ are susceptible to the aforementioned difficulties, the conventional TCM has limited applications. However, we remedy the internal resonance problem with a CFIE-based TCM, where $\overline{\mathbf{Z}}_{C}^{-1} \cdot \mathbf{u}$ can be iteratively solved with Krylov subspace methods such as generalized minimal residual (GMRES) method and biconjugate gradient (BiCG) method. Sparse approximate inverse (SAI), incomplete



Fig. 1. Point positions.

LU preconditioning, and even Calderoén multiplicative preconditioning schemes can be employed to expedite the convergence of CFIE solutions [25]–[27]. If the computational time is taken prior to other factors, it is promising to decompose $\overline{\mathbf{Z}}_C$ beforehand by leveraging fast direct methods with adequate memory provided [28], [29]. On the other hand, we circumvent difficulties in multiscale modeling of small complex objects with the A-EFIE-based TCM. If $\overline{\mathbf{Z}}_A^{-1} \cdot \mathbf{u}$ is iteratively solved with a constraint preconditioning scheme, MVPs can be efficiently computed with the LF-FMA [10].

VI. JDQZ FOR EFIE-BASED TCM

It is of interest to point out that for EFIE-based TCM, when (7) is used to compute characteristic modes, IRAM may be a less appropriate choice if the decomposition of $\overline{\mathbf{X}}_E$ is not available. This is due to the lack of efficiency in solving $\overline{\mathbf{X}}_E^{-1} \cdot \mathbf{u}$ with conventional preconditioners, such as SAI. However, the generalized eigenvalue problem (6) can be solved with the Jacobi–Davidson QZ (JDQZ) method [14]. Without converting (6) to (7), the correction vector t can be obtained by approximately solving the Jacobi–Davidson correction equation

$$(\overline{\mathbf{I}} - \overline{\mathbf{R}}_E \cdot \mathbf{u} \cdot \mathbf{u}^*) (\overline{\mathbf{X}}_E - \sigma \overline{\mathbf{R}}_E) (\overline{\mathbf{I}} - \mathbf{u} \cdot \mathbf{u}^* \cdot \overline{\mathbf{R}}_E) \mathbf{t} = - (\overline{\mathbf{X}}_E - \sigma \overline{\mathbf{R}}_E) \mathbf{u}, \quad \mathbf{t}^* \cdot \overline{\mathbf{R}}_E \cdot \mathbf{u} = 0$$
(31)

where $(\sigma, \mathbf{u} = \overline{\mathbf{V}}\mathbf{s})$ is a solution of

$$\overline{\mathbf{V}}^* \cdot \overline{\mathbf{X}}_E \cdot \overline{\mathbf{V}} \cdot \mathbf{s} = \sigma \overline{\mathbf{V}}^* \cdot \overline{\mathbf{R}}_E \cdot \overline{\mathbf{V}} \cdot \mathbf{s} = \sigma \mathbf{s}$$
(32)

with the search space $\overline{\mathbf{V}}$ containing several orthogonal basis with regard to $\overline{\mathbf{R}}_E$. The key is that even when (31) is solved with low accuracy, JDQZ still gives rise to correct solutions of (6). However, JDQZ becomes fairly slow in this case. Hence, it is also beneficial if efficient preconditioners are designed to accelerate the solutions of (31).

VII. NUMERICAL RESULTS

Numerical tests are first performed to validate the proposed plane-wave decompositions (24) and (29). We consider two cases as shown in Fig. 1, where the box size is a. In both cases, the source point j and source group center m' are located at (0.9999a, 1.0a, 0.0) and (0.5a, 0.5a, 0.5a), respectively. The observation point i and its group center m in Case 1 (dashed arrows) are located at (2.9999a, 0.0, 1.0a) and (2.5a, 0.5a, 0.5a), respectively, such that $|\mathbf{r}_{im} + \mathbf{r}_{m'j}| <$



Fig. 2. Relative error of plane-wave decomposition for the real and imaginary parts of Green's function with respect to a/λ .

 $|\mathbf{r}_{mm'}|$. The relative errors between left and right hand sides of (24) and (29) are calculated with respect to a/λ , where λ is the wavelength. The truncation number L is chosen to be

$$L \approx kd + 1.8d_0^{2/3} (kd)^{1/3} \tag{33}$$

where the number of digits of accuracy d_0 is set to 3, and $d = \sqrt{3}a$ in this test. As shown in Fig. 2, excellent agreement is observed except for (29) or $\cos(\cdot)$ at lower frequencies $(a < 0.5\lambda)$, which can be resolved with LF-FMA [20]. We then place the observation point *i* and its group center *m* at (1.0001a, 0.0, 0.0) and (1.5a, ;0.5a, 0.5a), respectively, in Case 2 (solid arrows) such that $|\mathbf{r}_{im} + \mathbf{r}_{m'j}| > |\mathbf{r}_{mm'}|$. As expected, (29) is no longer valid due to the violation of addition theorem. However, the regular part of the Green's function, i.e., $\sin(\cdot)$ can be computed with excellent accuracy (Fig. 2). This holds even when *i* and *j* are very close to each other. Although the results computed by (24) and (29) are not purely real, the imaginary parts are negligible as they are normally 10^{10} times smaller than the real parts.

The rest of numerical examples are computed with a nonparallel mixed-form FMA program on an Intel Core i5-2400 CPU with 3.10-GHz clock rate. Mixed-form FMA represents the field by multipoles for leafy levels in the quasi-static regime, and by plane waves for higher levels in the wave regime [10], [30]. In the rest of the examples, we use the plane-wave decomposition approach for the computation of $\overline{\mathbf{M}}_C \cdot \mathbf{u}$, and the direct algebraic approach for $\overline{\mathbf{X}}_A \cdot \mathbf{u}$. The open-source ARPACK package is employed as the iterative eigensolver unless specified otherwise. In this study, iterations in IRAM or JDQZ are referred to as outer iterations, and those in GMRES as inner iterations. Again, the free-space wavelength is denoted by λ .

A. Cuboid

We validate CFIE- and A-EFIE-based TCMs by computing characteristic modes of a perfectly conducting cuboid with a dimension of 1 m \times 0.9 m \times 0.3 m at 350 and 100 MHz, respectively. At 350 MHz, the triangular mesh comprises 1 280 patches and 1 920 edges, where the average edge length is around 0.08 λ . A few small characteristic values (CVs) are

TABLE I Characteristic Values (CVs) of Cuboid Computed by EFIE and CFIE at 350 MHz

CVs	EFIE	CFIE + FMA	Error (%)
$1+i\lambda_1$	1 + 0.3303i	1.0021 + 0.3310i	0.21
$1 + i\lambda_2$	1 + 0.3607i	1.0052 + 0.3563i	0.64
$1 + i\lambda_3$	1 - 0.3878i	1.0018 - 0.3861i	0.23
$1 + i\lambda_4$	1 + 0.4202i	1.0037 + 0.4174i	0.43
$1 + i\lambda_5$	1 + 0.5944i	1.0042 + 0.5921i	0.41
$1 + i\lambda_6$	1 - 0.6039i	1.0020 - 0.6007i	0.32
$1 + i\lambda_7$	1 + 0.6975i	1.0021 + 0.6993i	0.23
$1 + i\lambda_8$	1 - 0.7093i	1.0006 - 0.7040i	0.44



Fig. 3. Current patterns of mode J_1 at 350 MHz computed by (a) EFIE and (b) CFIE (0.9) + FMA.



Fig. 4. Far-field pattern of cuboid mode J_1 at 350 MHz.

computed with EFIE- and CFIE-based TCMs, namely (8) and (14), respectively, while FMA is only applied to CFIE of which the combination coefficient α is set to 0.9. The comparison is given in Table I, where good agreement is observed. Note that real parts of CVs resulted from CFIE are slightly different from 1. This is because, MFIE is not implemented to generate as accurate solutions as EFIE in this validation. On the other hand, EFIE- and CFIE-based TCMs yield the same characteristic modes. As an example, we plot in Fig. 3(a) and (b), the current patterns of J_1 obtained by the two methods, respectively. A comparison of normalized far field patterns of this current is given in Fig. 4, where good agreement is observed. When the error tolerance of GMRES iterations is set to 10^{-4} , the average numbers of inner iterations in each outer one are around 600 and 70 for EFIE and CFIE, respectively, as a simple near-neighbor preconditioner is used.

To validate the A-EFIE-based TCM that addresses densely meshed objects that are not electrically large, we bring down the operating frequency to 100 MHz. To generate a reference, the

TABLE II CHARACTERISTIC VALUES (CVS) OF CUBOID COMPUTED BY EFIE AND A-EFIE AT 100 MHz

CVs	EFIE	A-EFIE + FMA	Error (%)
λ_1	0.5992	0.5959	0.55
λ_2	0.8960	0.8910	0.56
λ_3	-4.3001	-4.2893	0.25
λ_4	6.4258	6.4091	0.26
λ_5	-8.5905	-8.5718	0.22
λ_6	-8.6574	-8.6409	0.19
λ_7	10.6119	10.5448	0.63
λ_8	30.2488	30.2052	0.14



Fig. 5. Current patterns of mode J_1 at 100 MHz computed by (a) EFIE and (b) A-EFIE + FMA.



Fig. 6. Far-field pattern of cuboid mode J_1 at 100 MHz.

original mesh is used with the EFIE-based formula (8) with an average edge length of 0.023λ . A finer mesh containing 4 210 triangular patches and 6 315 inner edges is used with (19) based on A-EFIE, where the average edge length becomes 0.015λ . As shown in Table II, characteristic values (CVs) obtained by EFIE agree well with those computed with A-EFIE and LF-FMA. We also find that characteristic currents generated by the two methods are consistent. For example, current patterns of J₁ computed by EFIE and A-EFIE are plotted in Fig. 5(a) and (b), respectively. Their normalized far-field patterns are demonstrated in Fig. 6. A good agreement can be observed in both the current and far-field plots.

This example is also adopted to demonstrate the performance of JDQZ. In JDQZ, one can obtain correct characteristic values even with a small number of inner iterations (dimension of search space in GMRES), which indicates that (31) is only solved with poor accuracy each time. JDQZ and the original mesh are used to solve for five characteristic modes of the same



Fig. 7. Number of JDQZ iterations with respect to the dimension of GMRES searchspace.



Fig. 8. Characteristic currents of a NASA almond. (a) J_1 . (b) J_2 . (c) J_3 . (d) J_4 . Their characteristic values are -0.0271, 0.0644, 0.0680, and 0.0768, respectively.

cuboid at 350 and 100 MHz, respectively. The convergence tolerance in JDQZ is set to 10^{-4} , which guarantees to generate correct characteristic modes. Fig. 7 shows the required number of outer (JDQZ) iterations with respect to the search space dimension of GMRES. Although a small search space reduces the computational time of each outer iteration, the tradeoff is that it increases the total number of outer iterations.

B. NASA Almond

We then consider a NASA almond that has a dimension of $5.05 \lambda \times 1.95 \lambda \times 0.65 \lambda$ at 60 MHz. The mesh contains 36 090 triangular patches and 54 135 inner edges, and the average edge length is 0.0326λ . To solve the CFIE-based eigenvalue problem (14), the CFIE combination coefficient is set to 0.5, and the GMRES error tolerance is set to 10^{-4} . The first four characteristic modes are computed by a six-level MLFMA using about 730-MB RAM, and their current patterns are plotted in Fig. 8. A typical convergence history of computing MVPs $\overline{\mathbf{Z}}_E^{-1} \cdot \mathbf{u}$ and $\overline{\mathbf{Z}}_C^{-1} \cdot \mathbf{u}$ with GMRES and near-neighbor preconditioning



Fig. 9. Typical convergence history of inner (GMRES) iterations with EFIE and CFIE.

in an outer iteration is shown in Fig. 9, which clearly demonstrates the advantage of the proposed CMA. In [11], where a few modes of a vehicle $(0.5 \lambda \times 0.23 \lambda \times 0.25 \lambda)$ with 9706 unknowns are computed with the EFIE-based formula (7), the memory usage is 3.54 and 2.8 GB for QZ factorization and IRAM, respectively. It is obvious that our scheme enables CMA of larger scale applications on a small computer.

Note that we herein are not considering extremely electrically large applications, because a great number of modes are needed for mode expansion, which renders CMA less useful. However, our method reserves the capability to address such challenging problems, provided that the direct decomposition of the full-rank matrix $\overline{\mathbf{Z}}_C$ is available.

C. Spiral Antenna

The next example is a spiral antenna with a dimension of $0.4 \lambda \times 0.4 \lambda \times 0.08 \lambda$ at 1.64 GHz, where a dense mesh containing 60 552 triangular patches and 82 524 inner edges is used. The minimum, maximum, and average edge lengths are $0.169 \times 10^{-3} \lambda$, $0.733 \times 10^{-2} \lambda$, and $0.154 \times 10^{-2} \lambda$, respectively. The A-EFIE-based scheme is performed with a six-level LF-FMA, where the average number of GMRES iterations is 98 for the error tolerance of 1×10^{-4} with the usage of a constraint preconditioner. In this simulation, roughly 810-MB RAM is used to find five lowest modes. The current and radiation power patterns of a dipole mode, e.g., J_3 , and a quadrupole mode, e.g., J_4 , are plotted in Fig. 10(a)–(d), respectively. For comparison, we perform an EFIE-based CMA of the same antenna using a coarse mesh with 7 324 inner edges, where both matrices $\overline{\mathbf{R}}_E$ and $\overline{\mathbf{X}}_E$ are explicitly stored. When (7) is solved with the built-in MATLAB function eigs which implements IRAM, the memory usage is around 3.48 GB. A good agreement is observed between the characteristic values and normalized power patterns obtained by these two schemes, as shown in Table III and Fig. 11, respectively.

D. Package Board

In the last example, we consider a densely meshed model that is cut out of a realistic package board that contains two interconnect pairs. The triangular mesh has 79 480 patches and 114 240 inner edges, which leads to 193 719 unknowns



Fig. 10. Characteristic modes of a spiral antenna. (a) J_3 . (b) J_4 . (c) Power pattern of J_3 . (d) Power pattern of J_4 .



Fig. 11. Normalized power patterns of spiral antenna modes J_3 and J_4 computed by EFIE and A-EFIE at: (a) *xy*-plane ($\theta = 90^\circ$) and (b) *xz*-plane ($\phi = 0^\circ$).

TABLE III Characteristic Values of Spiral Antenna Computed by EFIE and A-EFIE at 1.64 GHz

CVs	EFIE	A-EFIE + LF-FMA	Error (%)
λ_1	2.1022	2.1511	2.33
λ_2	2.1022	2.1508	2.31
λ_3	-2.9582	-2.9739	0.53
λ_4	25.6066	25.5428	0.25
λ_5	53.7648	54.3620	1.11

in this simulation. The entire structure is around 0.2λ along the largest dimension at 3 GHz. The minimum, maximum, and average edge lengths are $0.454 \times 10^{-5} \lambda$, $0.368 \times 10^{-2} \lambda$, and $0.744 \times 10^{-3} \lambda$, respectively. The GMRES error tolerance is set to 0.15×10^{-4} , and on average, each outer iteration takes about 105 inner iterations for GMRES to converge as a constraint preconditioner is used. Totally, 120 (more than



Fig. 12. Characteristic currents of a package board part. (a) J_1 . (b) J_2 . (c) J_3 . (d) J_4 . Their characteristic values are 19.5, 73.0, -121.0, and 1960.3, respectively.

enough) Arnoldi vectors are generated to compute four dominant characteristic modes. Their current patterns are illustrated in Fig. 12, where the characteristic values are also provided. The direct residuals of such eigensolutions are less than 10^{-3} . With the usage of a seven-level LF-FMA, the memory cost in this computation is less than 1 GB, and the CPU time is about 6 h.

VIII. CONCLUSION

In this article, we address large-scale CMA with FMAs. As the EFIE-based TCM is susceptible to the corruption of spurious internal resonances, we incorporate multilevel (ML-) FMA with a CFIE-based TCM to compute the modes of large closed conducting surfaces. The standard MLFMA program can be easily modified to perform the required matrix–vector multiplication operations in the iterative eigensolvers. On the other hand, an A-EFIE-based TCM is also developed for analyzing multiscale structures. By incorporating LF-FMA, it enables one to perform CMA for densely meshed objects that are not electrically large but contain fine components. Several numerical examples are provided to demonstrate the validity and efficiency of the proposed schemes. In even larger scale simulations, FMA can be implemented in parallel on many processors for better performance.

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